# The ANYNT Project Intelligence Test $\Lambda_{one}$

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- Measuring intelligence universally
- Precedents
- Λ<sub>one</sub> Test setting
- Testing AI performance
- Testing different systems
- Discussion

Outline

### Measuring intelligence universally



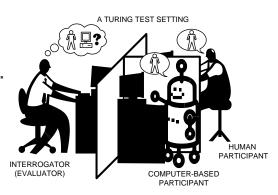
Can we construct a 'universal' intelligence test?

Project: anYnt (Anytime Universal Intelligence)

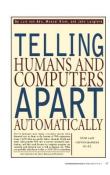
http://users.dsic.upv.es/proy/anynt/

- Any kind of system (biological, non-biological, human).
- Any system now or in the future.
- Any moment in its development (child, adult).
- Any degree of intelligence.
- Any speed.
- Evaluation can be stopped at any time.

- Imitation Game "Turing Test" (Turing 1950):
  - It is a test of *humanity*, and needs human intervention.
  - Not actually conceived to be a practical test for measuring intelligence up to and beyond human intelligence.



- CAPTCHAs (von Ahn, Blum and Langford 2002):
  - Quick and practical, but strongly biased.
  - They evaluate *specific* tasks.
  - They are not conceived to evaluate intelligence, but to tell humans and machines apart at the current state of Al technology.
  - It is widely recognised that CAPTCHAs will not work in the future (they soon become obsolete).



Type the characters you see in the picture below.



- Tests based on Kolmogorov Complexity (compression-extended Turing Tests, Dowe 1997a-b, 1998) (C-test, Hernandez-Orallo 1998).
  - Look like IQ tests, but formal and well-grounded.
  - Exercises (series) are not arbitrarily chosen.
  - They are drawn and constructed from a universal distribution, by setting several 'levels' for *k*:

```
k = 9 : a, d, g, j, ... Answer: m

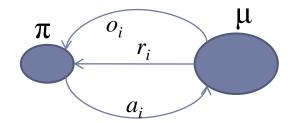
k = 12 : a, a, z, c, y, e, x, ... Answer: g

k = 14 : c, a, b, d, b, c, c, e, c, d, ... Answer: d
```

- However...
  - Some relatively simple algorithms perform well in IQ-like tests (Sanghi and Dowe 2003).
  - They are static (no planning abilities are required).

Universal Intelligence (Legg and Hutter 2007): an interactive extension to C-tests from sequences to environments.

$$\Upsilon(\pi, U) = \sum_{\mu=i}^{\infty} p_U(\mu) \cdot E\left(\sum_{i=1}^{\infty} r_i^{\mu, \pi}\right)$$



- = performance over a universal distribution of environments.
- Universal intelligence provides a definition which adds interaction and the notion of "planning" to the formula (so intelligence = learning + planning).
  - ▶ This makes this apparently different from an IQ (static) test.

#### Kolmogorov Complexity

$$K_U(x) := \min_{\substack{p \text{ such that } U(p)=x}} l(p)$$

where I(p) denotes the length in bits of p and U(p) denotes the result of executing p on U.

#### Universal Distribution

Given a prefixed-free machine U, the universal probability of string x is defined as:

$$p_U(x) := 2^{-K_U(x)}$$

Levin's Kt Complexity

$$Kt_U(x) := \min_{p \text{ such that } U(p) = x} \{ l(p) + \log time(U, p, x) \}$$

where l(p) denotes the length in bits of p and U(p) denotes the result of executing p on U, and time(U,p,x) denotes the time that U takes executing p to produce x.

Time-weighted Universal Distribution

Given a prefix-free machine U, the universal probability of string x is defined as:

$$p_U(x) := 2^{-Kt_U(x)}$$

A definition of intelligence does not ensure an intelligence test.

Anytime Intelligence Test (Hernandez-Orallo and Dowe 2010):

An interactive setting following (Legg and Hutter 2007) which addresses:

Issues about the difficulty of environments.

The definition of discriminative environments.

☐ Finite samples and (practical) finite interactions.

☐ Time (speed) of agents and environments.

Reward aggregation, convergence issues.

Anytime and adaptive application.

An environment class  $\Lambda$  (Hernandez-Orallo 2010).

## $\Lambda_{one}$ Test setting

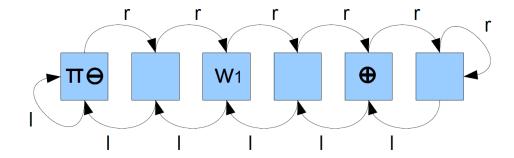
- Discriminative environments.
- Interact infinitely: Must be a pattern (Good and Evil).
- Balanced environments.
  - Symmetric rewards.

$$\forall i: -1 \leq r_i \leq 1$$

- Symmetric behaviour for Good and Evil.
- Agents have influence on rewards: Sensitive to agents' actions.

### $\Lambda_{one}$ Test setting

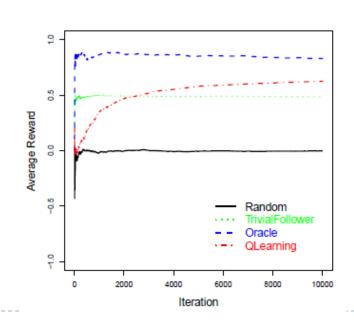
- Implementation of the environment class:
  - Spaces are defined as fully connected graphs.
    - Actions are the arrows in the graphs.
    - Observations are the 'contents' of each edge/cell in the graph.



- Agents can perform actions inside the space.
- Rewards: Two special agents Good (⊕) and Evil (⊝), which are responsible for the rewards.

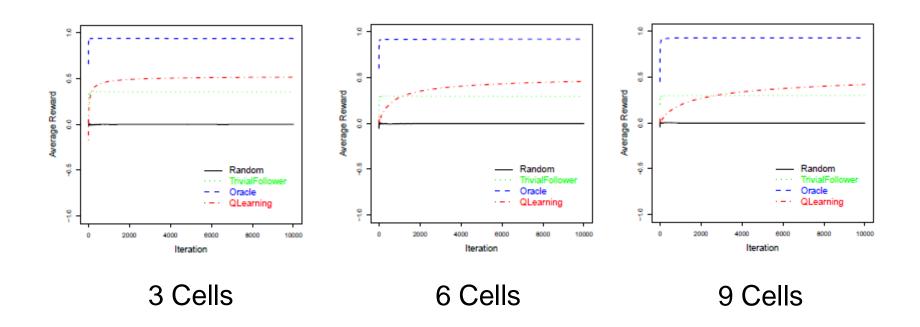
### Testing AI performance

- ▶ Test with 3 different complexity levels (3,6,9 cells).
  - We randomly generated 100 environments for each complexity level with 10,000 interactions.
  - Size for the patterns of the agents Good and Evil (which provide rewards) set to 100 actions (on average).
- Evaluated Agents:
  - Q-learning
  - Random
  - Trivial Follower
  - Oracle



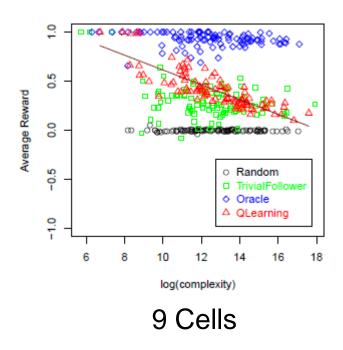
### Testing AI performance

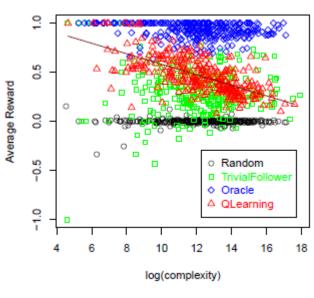
- Experiments with increasing complexity.
  - Results show that Q-learning learns slowly with increasing complexity.



### Testing AI performance

- Analysis of the effect of complexity:
  - Complexity of environments is approximated by using (Lempel-Ziv) LZ(concat(S,P)) x |P|.





All environments

Inverse correlation with complexity (difficulty ↑, reward ↓).

Each agent must have an appropriate interface that fits its needs (Observations, actions and rewards):

Al agent

b:E:πGa::

+1.0

Biological agent: 20 humans











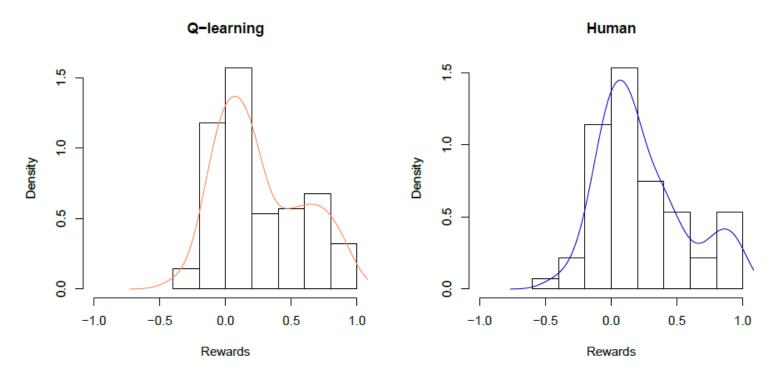


- We randomly generated only 7 environments for the test:
  - Different topologies and sizes for the patterns of the agents Good and Evil (which provide rewards).
  - Different lengths for each session (exercise) accordingly to the number of cells and the size of the patterns.

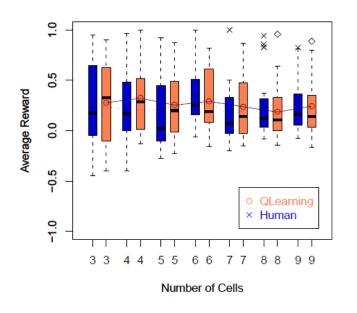
Env. #	No. cells $(n_c)$	No. steps (m)	Pattern length (on average)
1	3	20	3
2	4	30	4
3	5	40	5
4	6	50	6
5	7	60	7
6	8	70	8
7	9	80	9
TOTAL	-	350	-

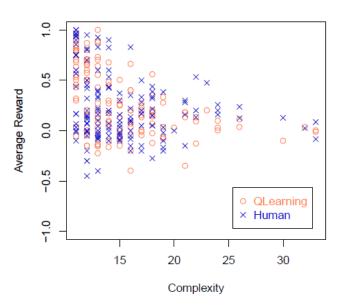
The goal was to allow for a feasible administration for humans in about 20-30 minutes.

- Experiments were paired.
  - Results show that performance is fairly similar.



- Analysis of the effect of complexity :
  - Complexity is approximated by using LZ (Lempel-Ziv) coding to the string which defines the environment.





- Lower variance for exercises with higher complexity.
- ▶ Slight inverse correlation with complexity (difficulty  $\uparrow$ , reward  $\downarrow$ ).

#### Discussion

- Environment complexity is based on an approximation of Kolmogorov complexity and not on an arbitrary set of tasks or problems.
  - So it's not based on:
    - Aliasing
    - Markov property
    - Number of states
    - Dimension
    - **...**
- The test aims at using a Turing-complete environment generator but it could be restricted to specific problems by using proper environment classes.
- An implementation of the Anytime Intelligence Test using the environment class  $\Lambda$  can be used to evaluate AI systems.

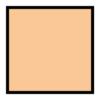
#### Discussion

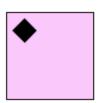
- The test is not able to evaluate different systems and put in the same scale. The results show *this is not a universal intelligence test*.
- What may be wrong?
  - A problem of the current implementation. Many simplifications made.
  - A problem of the environment class.
  - A problem of the environment distribution.
  - A problem with the interfaces, making the problem very difficult for humans.
  - A problem of the theory.
    - Intelligence cannot be measured universally.
    - Intelligence is factorial. Test must account for more factors.
    - Using algorithmic information theory to precisely define and evaluate intelligence may be insufficient.

### Thank you!

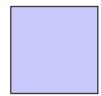
#### Some pointers:

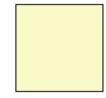
- Project: anYnt (Anytime Universal Intelligence)
   <a href="http://users.dsic.upv.es/proy/anynt/">http://users.dsic.upv.es/proy/anynt/</a>
- Have fun with the test.













http://users.dsic.upv.es/proy/anynt/human1/test.html